

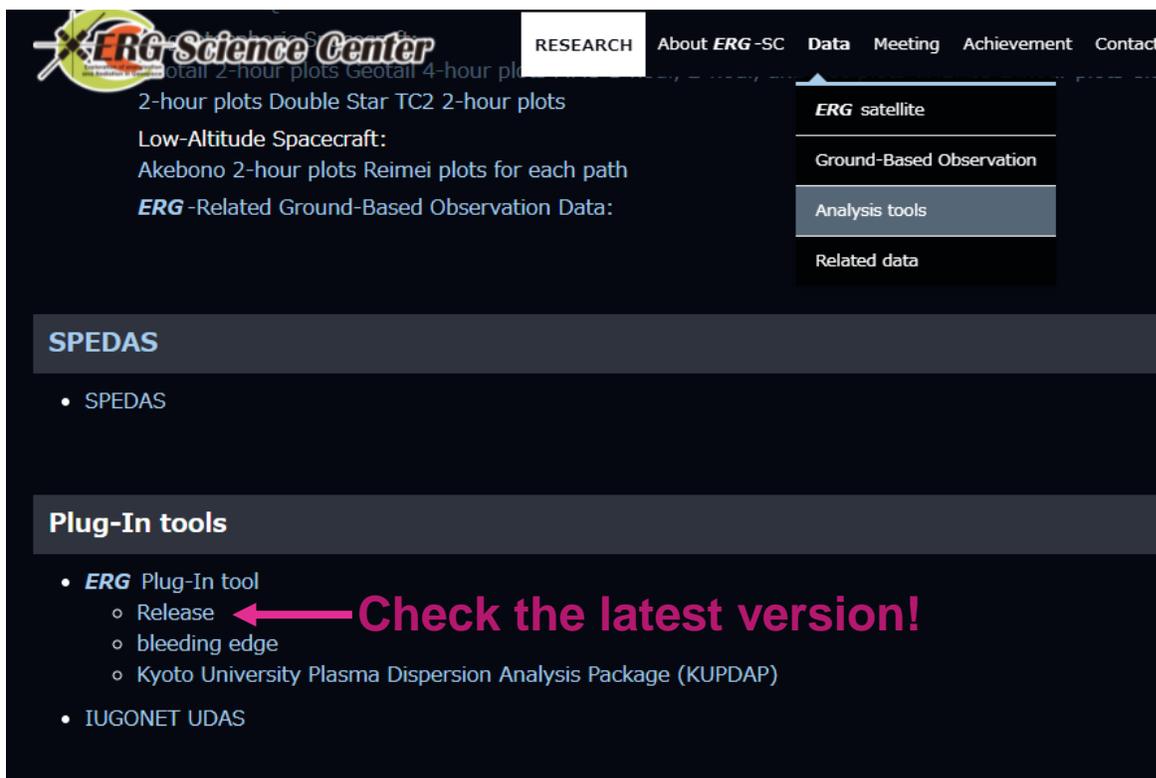
SPEDAS training course - ERG orbit -

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SPEDAS training session, Oct. 13, 2021

Before this training course

- This course will use ERG plug-in tool based on IDL SPEDAS.
- Please update your ERG plug-in as the latest version.
- ERG Science center provides lectures for the beginners of IDL SPEDAS on our Youtube channel. ([url:https://www.youtube.com/channel/UCuklaSJ1I-KbZnVzYNmgIVg](https://www.youtube.com/channel/UCuklaSJ1I-KbZnVzYNmgIVg))
- If you utilize ERG orbit data for your study, please cite ERG orbit DOI on your publication.
- If you have any questions, please feel free to contact “[ergsc-help at isee.nagoya-u.ac.jp](mailto:ergsc-help@isee.nagoya-u.ac.jp)”.



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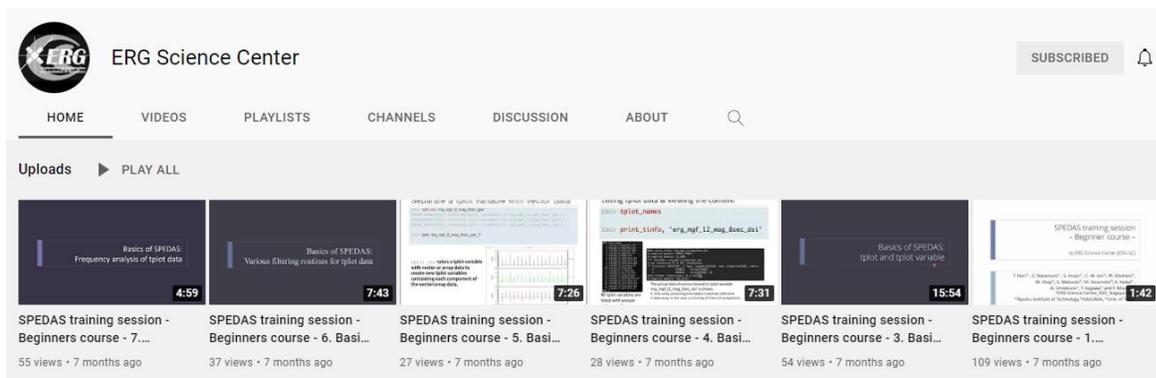
2-hour plots Double Star TC2 2-hour plots
Low-Altitude Spacecraft:
Akebono 2-hour plots Reimei plots for each path
ERG-Related Ground-Based Observation Data:

SPEEDAS

- SPEEDAS

Plug-In tools

- ERG Plug-In tool
 - Release ← Check the latest version!
 - bleeding edge
 - Kyoto University Plasma Dispersion Analysis Package (KUPDAP)
- IUGONET UDAS



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Goal of this training



- We are going to learn how to load, and plot orbit data of the ERG satellite, with a special focus on plotting satellite trajectories in space and ionospheric footprints on the world map.

Contents of this course

- Information of ERG orbit dataset
- Plot orbit data
 1. Time series using “tplot”
 2. Satellite trajectory in XY or XZ plane
 3. Ionospheric footprints on the world map
- Appendix
 1. Information of coordinate system
 2. Meaning of L_m and L^*

ERG orbit dataset

Web data repository →

Scientific data				
Orbit Data				
Predicted Orbit	Short-term	CDF file	wiki	
	Mid-term	CDF file		
	Long-term	CDF file		
Definitive Orbit	Lv.2 definitive orbit data	CDF file	wiki	DOI: 10.34515/DATA.ERG-12000 (Lv.2 definitive orbit data)
	Lv.3 definitive orbit data	CDF file		DOI: 10.34515/DATA.ERG-12001 (Lv.3 definitive orbit data)

Level	Datatype or model	Load procedure
L2 (IGRF)	Definitive	erg_load_orb
	Predict (pre, spre, mpre, lpre)	erg_load_orb_predict, datatype = 'pre, spre, mpre, lpre'
L3 (IGRF + external fields)	OP77Q model using quiet time model	erg_load_orb_l3, model='op or t89 or ts04'
	T89 model using Kp index	
	TS04 model using IMF + Dst index	

* Note: the information of L* and invariant is only provided by l3 orbit data set.

Plot ERG orbit data:1. Time series using “tplot”

```
; Set the time range to 9-18 UT on Sep. 21, 2019
```

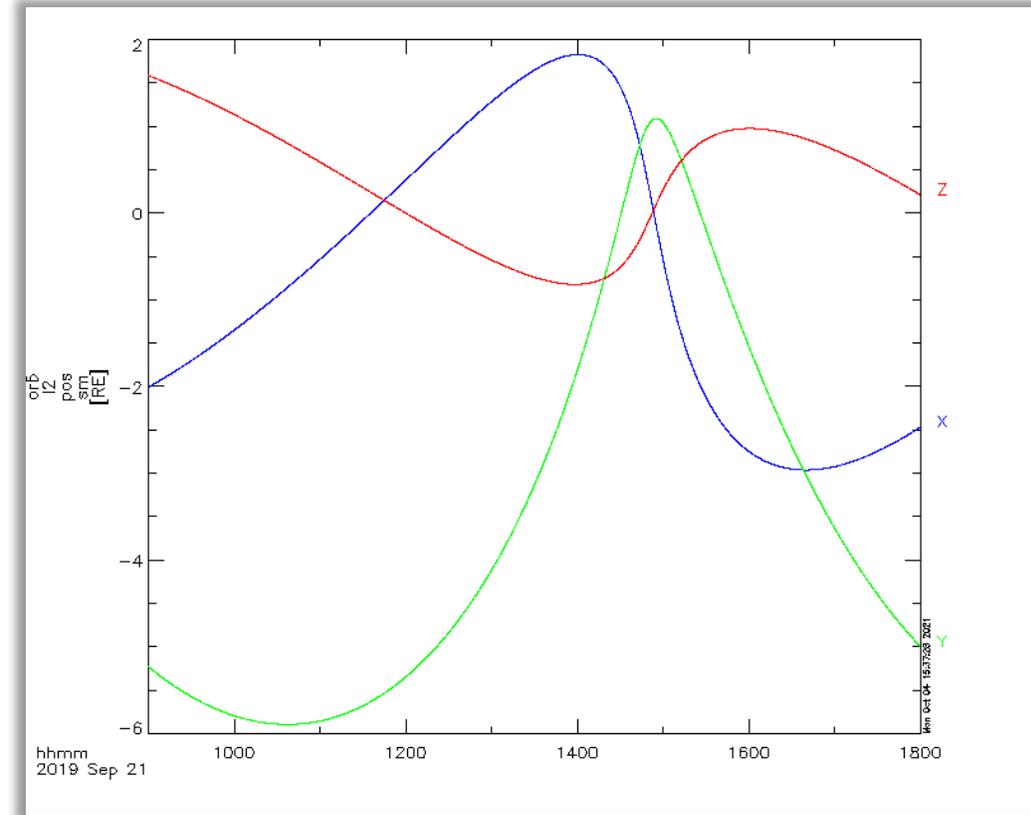
```
IDL> timespan,'2019-09-21/09:00:00',9,/hour
```

```
; Load Arase I2 def orbit data
```

```
IDL> erg_load_orb
```

```
; Plot Arase orbit in the SM coord.
```

```
IDL> tplot,'erg_orb_I2_pos_sm'
```



2. Satellite trajectory in XY or XZ plane

; Set the time range to 9-18 UT on Sep. 21, 2019

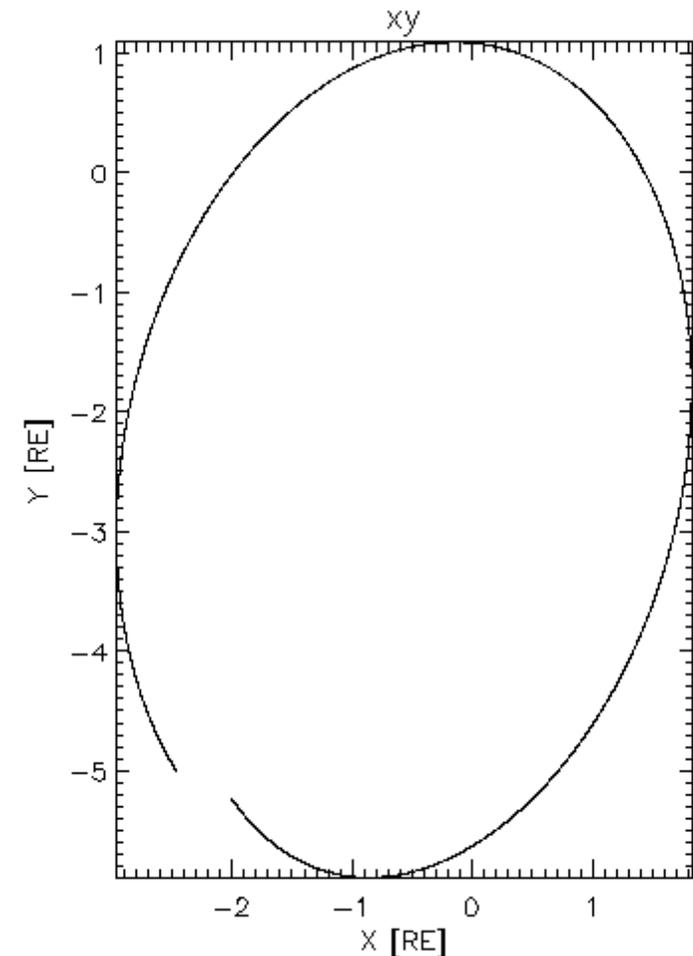
```
IDL> timespan,'2019-09-21/09:00:00',9,/hour
```

; Load Arase I2 def orbit data

```
IDL> erg_load_orb
```

; Plot Arase orbit on the SM X-Y plane

```
IDL> tplotxy,'erg_orb_I2_pos_sm'
```



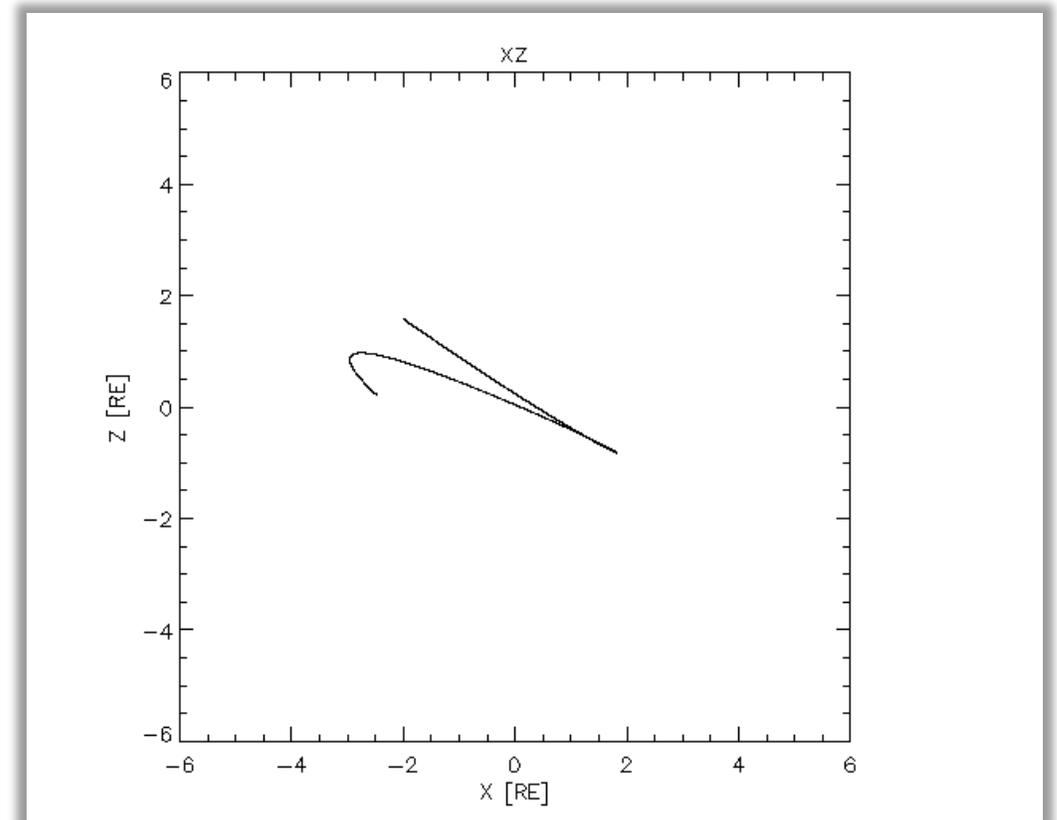
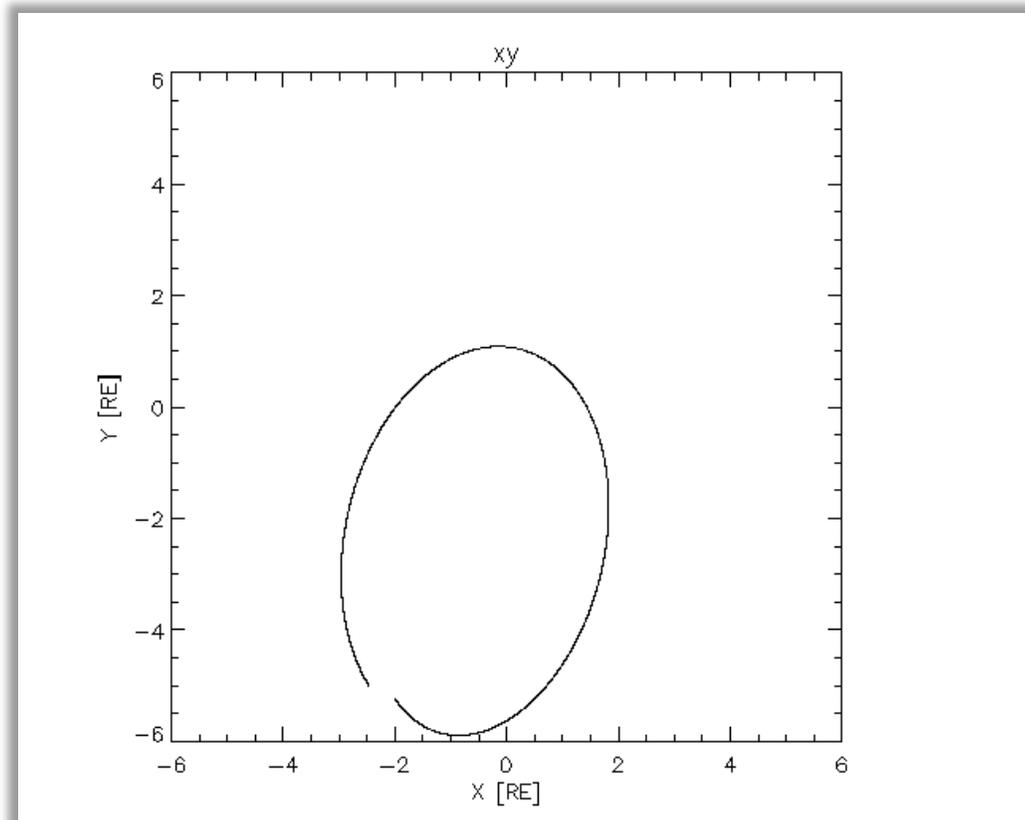
2. Satellite trajectory in XY or XZ plane (cont'd)

; Plot Arase orbit on the X-Y plane of $-6 \text{ Re} < x, y < 6 \text{ Re}$

```
IDL> tplotxy,'erg_orb_l2_pos_sm',versus='xy',xrange = [-6,6],yrange = [-6,6]
```

; The same but on the X-Z plane

```
IDL> tplotxy,'erg_orb_l2_pos_sm',versus='xz',xrange = [-6,6],yrange = [-6,6]
```



Additional information for “**tplotxy**” and “**plotxy**”

tplotxy, tplot_variable_name\$; (e.g., 'position_sm')

- , versus='xy' ; choose axis (e.g., xy or xz)
- , multi= 'n_col n_raw' ; make multi plots ('# of column # of row')
- , over = over ; overplot on the current window
- , add = add ; add plot
- , additional plot options ; (e.g., title, xrange, color, linestyle, etc.)

plotxy, variable\$; position array ([time,#_of_axis])

- , versus='xy' ; choose axis (e.g., xy or xz)
- , multi= 'n_col n_raw' ; make multi plots ('# of column # of row')
- , over = over ; overplot on the current window
- , add = add ; add plot
- , additional plot options ; (e.g., title, xrange, color, linestyle, etc.)

3. Ionospheric footprints on the world map

; Initialize the map2d environment and Set the coordinate system to geographical coordinate

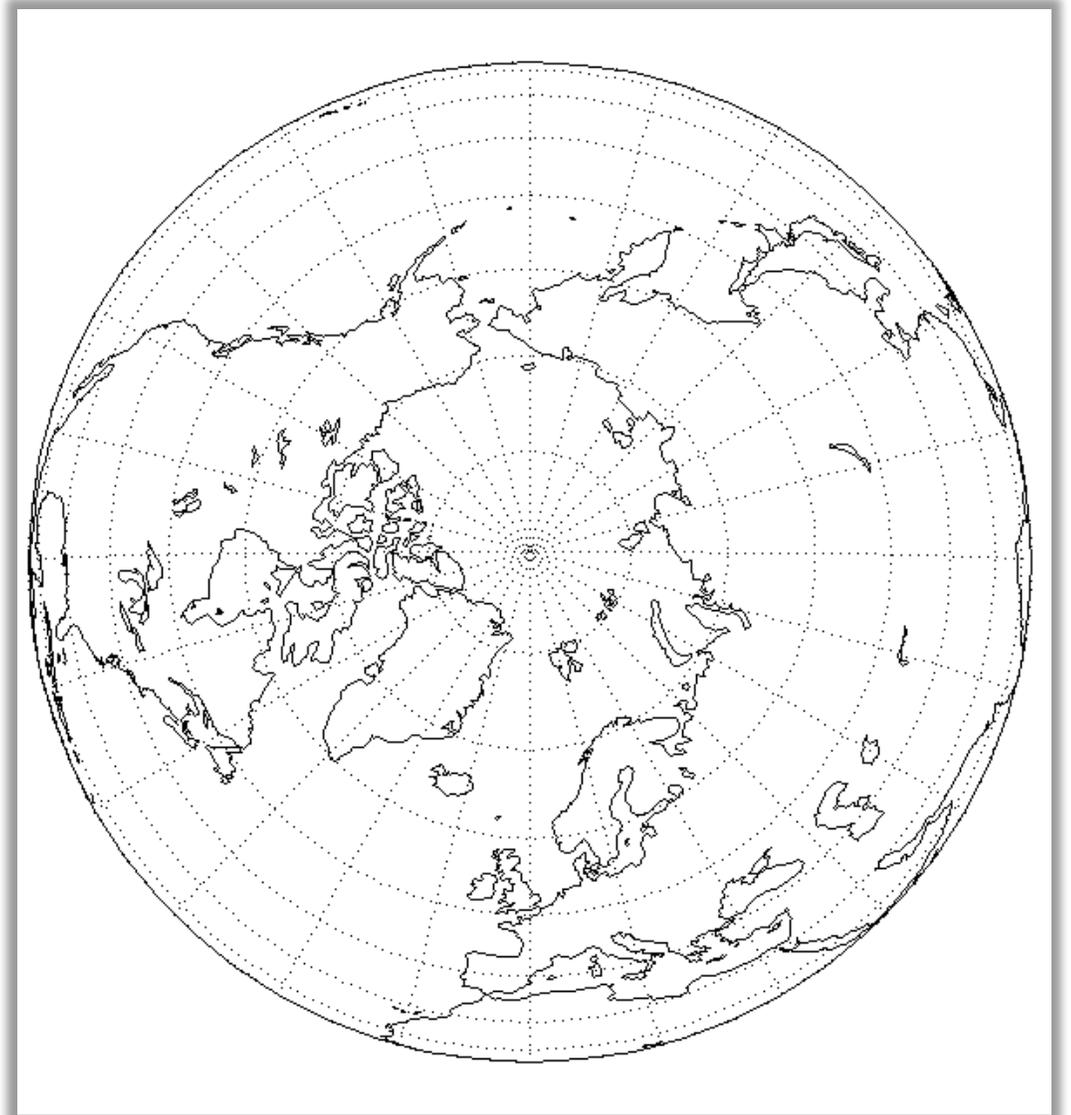
```
IDL> map2d_init & map2d_coord, 'geo'
```

; Generate an empty window

```
IDL> window, 0, xsize=800, ysize=640 & erase
```

; Draw the grid (10 deg in lat & 15 deg in log) on the window and Draw the coast lines

```
IDL> map2d_set & overlay_map_coast
```



3. Ionospheric footprints on the world map (cont'd)

```
; get I2 data for ionospheric footprints on the  
northern hemisphere
```

```
IDL> erg_load_orb
```

```
IDL> get_data, 'erg_orb_l2_pos_iono_north',  
data=data_foot
```

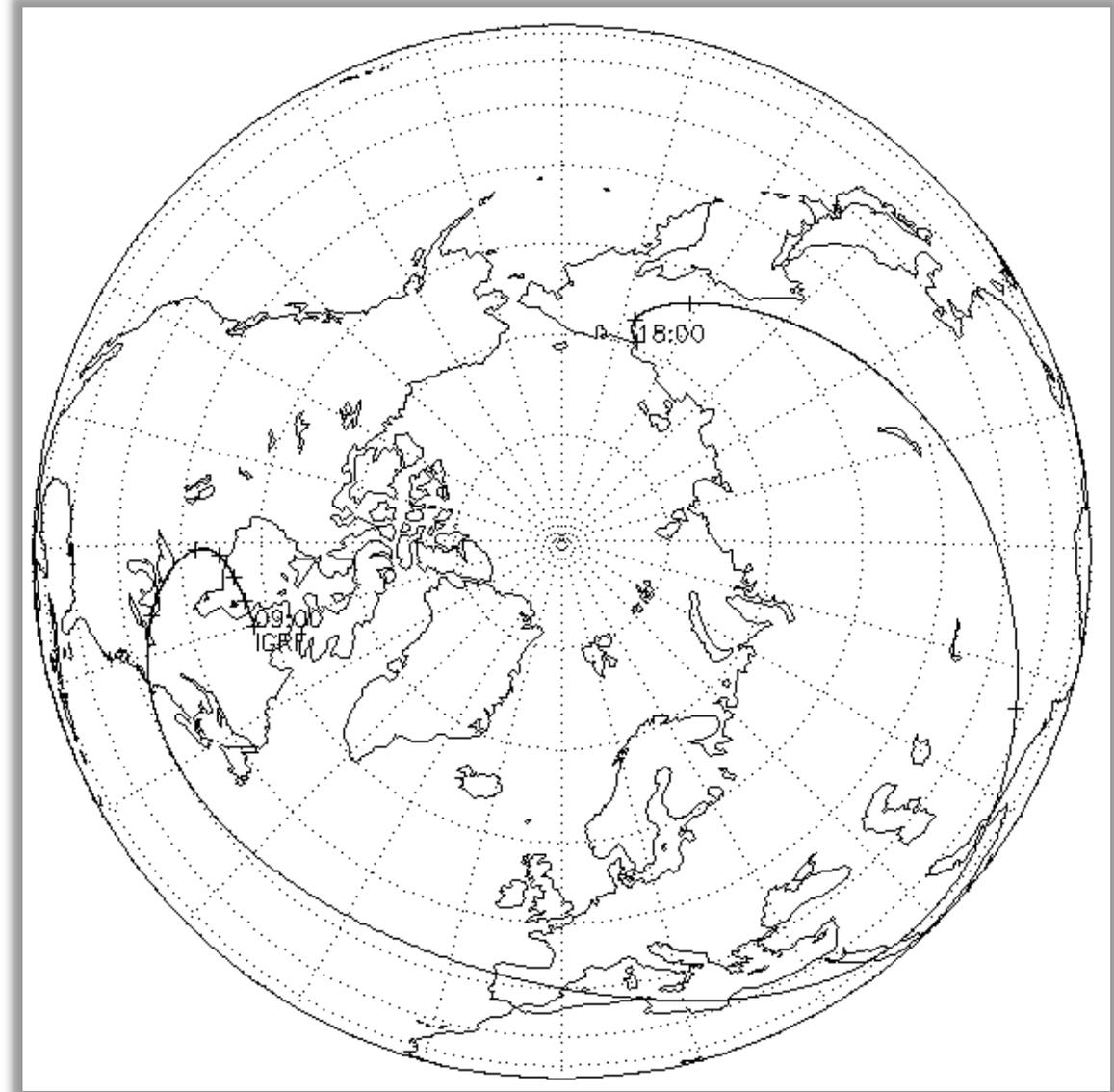
```
; Store latitude and longitude separately.
```

```
IDL> store_data, 'IGRF_ifoot_glat', data=  
{x:data_foot.x, y:reform(data_foot.y[*], 0)}
```

```
IDL> store_data, 'IGRF_ifoot_glog', data=  
{x:data_foot.x, y:reform(data_foot.y[*], 1)}
```

```
; Overplot Arase footprint on the map
```

```
IDL> overlay_map_sc_ifoot, 'IGRF_ifoot_glat',  
'IGRF_ifoot_glog'
```



Comparison of footprints using different models

```
; get I3 OP77Q orbit data for ionospheric footprints
```

```
IDL> erg_load_orb_l3,model = 'op' & get_data, 'erg_orb_l3_pos_iono_north_op', data=data_foot_op
```

```
IDL> store_data, 'OP77Q_ifoot_glat',data= {x:data_foot_op.x, y:reform(data_foot_op.y[*],0)}
```

```
IDL> store_data, 'OP77Q_ifoot_glog',data= {x:data_foot_op.x, y:reform(data_foot_op.y[*],1)}
```

```
; get I3 T89 orbit data for ionospheric footprints
```

```
IDL> erg_load_orb_l3,model = 't89' & get_data, 'erg_orb_l3_pos_iono_north_t89', data=data_foot_t89
```

```
IDL> store_data, 'T89_ifoot_glat',data= {x:data_foot_t89.x, y:reform(data_foot_t89.y[*],0)}
```

```
IDL> store_data, 'T89_ifoot_glog',data= {x:data_foot_t89.x,y:reform(data_foot_t89.y[*],1)}
```

```
; get I3 TS04 orbit data for ionospheric footprints
```

```
IDL> erg_load_orb_l3,model = 'ts04' & get_data, 'erg_orb_l3_pos_iono_north_TS04',  
data=data_foot_ts04
```

```
IDL> store_data, 'TS04_ifoot_glat',data= {x:data_foot_ts04.x, y:reform(data_foot_ts04.y[*],0)}
```

```
IDL> store_data, 'TS04_ifoot_glog',data= {x:data_foot_ts04.x,y:reform(data_foot_ts04.y[*],1)}
```

Comparison of footprints using different models (cont'd)

; Generate a new map window

```
IDL> window, 0, xsize=800, ysize=640 & erase
```

```
IDL> map2d_set, glonc = 280, glatc=60, scale = 1e7 &  
overlay_map_coast
```

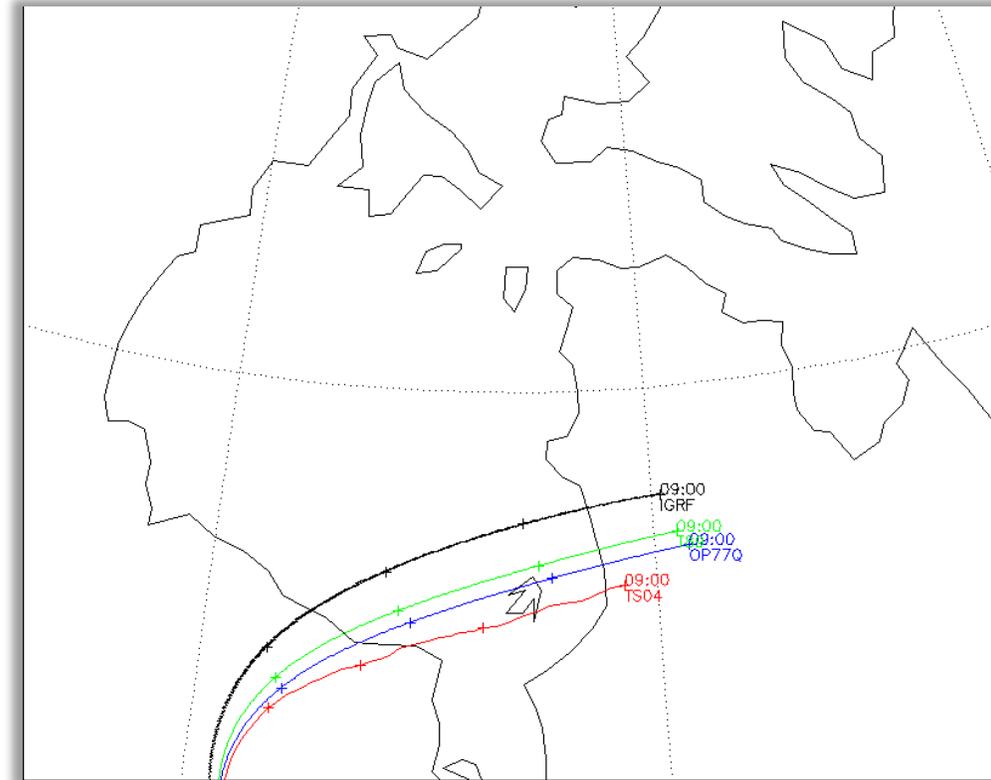
; Overplot Arase footprints using different models

```
IDL> overlay_map_sc_ifoot, 'IGRF_ifoot_glat',  
'IGRF_ifoot_glog'
```

```
IDL> overlay_map_sc_ifoot, 'OP77Q_ifoot_glat',  
'OP77Q_ifoot_glog', trace_color=2
```

```
IDL> overlay_map_sc_ifoot, 'T89_ifoot_glat',  
'T89_ifoot_glog', trace_color=4
```

```
IDL> overlay_map_sc_ifoot, 'TS04_ifoot_glat',  
'TS04_ifoot_glog', trace_color=6
```



Additional information for “**map2d_set**” and “**overlay_map_sc_ifoot**”

Map2d_set, glatc=value, glonc=value, scale=value, coord='...', /set_time, /nogrid

Keywords:

- glatc (glonc): geographical latitude (longitude) at which a plot region is centered.
(both glatc and glonc should be given, otherwise ignored)
- scale: same as the keyword "scale" of map_set
- coord: name of the coordinate system.
('geo' or 0 for Geographic coordinate. 'aacgm' or non-zero numbers for AACGM coordinate.)
- set_time: this is used to calculate MLT when coord is 'aacgm'
- mllabel: set to draw the MLT labels every 2 hour.
- nogrid: set to suppress drawing the lat-lon mesh
- dlat(dlong)_grid: set grid steps for latitude (longitude) (default: 10 deg in lat & 15 deg in log)

Overlay_map_sc_ifoot, tplot_variable_lat, tplot_variable_lon \$

, ['YYYY-MM-DD/hh:mm', 'YYYY-MM-DD/hh:mm'] ; time range

, trace_color = integer ; Set a color of the line

Summary

- Load procedure of ERG orbit data
 - **erg_load_orb** → I2 definitive orbit data
 - **erg_load_orb_predict** → I2 predicted orbit data (datatype: pre, spre, mpre, lpre)
 - **erg_load_orb_I3** → I3 definitive orbit data (model: OP77Q, T89, TS04)

- Plot ERG orbit
 - Time-series plot → **tplot**
 - Projection of orbit trajectories on 2D plane → **tplotxy** (or **plotxy**)
 - Projection of ionospheric footprints on the map
 1. Initialize map setting
 2. Draw the map on the window
 3. load and store ionospheric footprint information
 4. Plot ionospheric footprints using “**overlay_map_sc_ifoot**”

Appendix

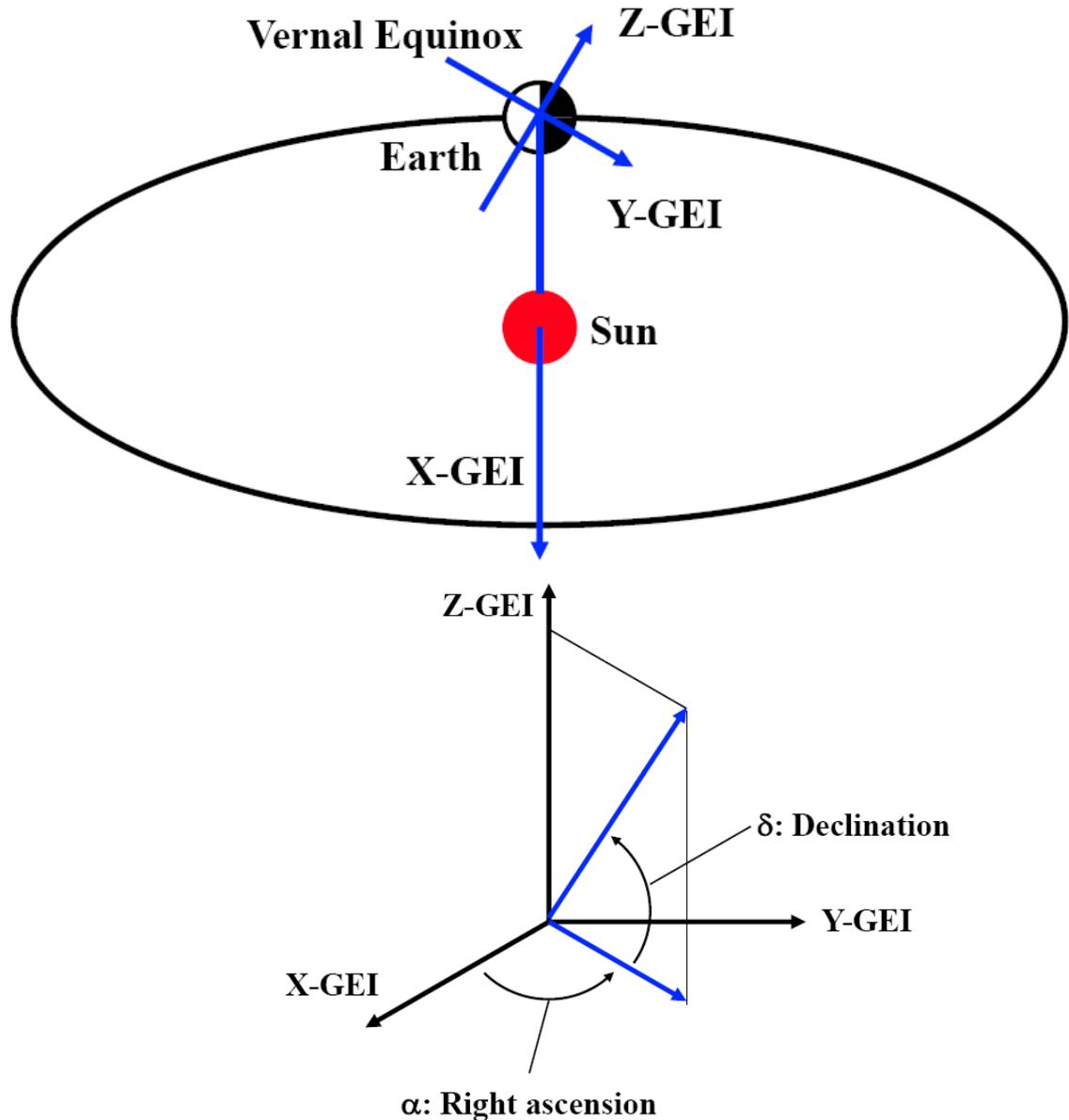
1. Information of geomagnetic coordinate system

Coord. System	Aberration	Usage
Geocentric Equatorial Inertial	GEI	Astronomy, satellite orbits
Geographic	GEO	Position of ground stations
Geomagnetic	MAG	Position of geomagnetic observations
Geocentric Solar Ecliptic	GSE	Satellite trajectories, Solar wind
Geocentric Solar Magnetospheric	GSM	Magnetospheric fields in the outer magnetosphere
Solar Magnetic	SM	Magnetospheric fields in the inner magnetosphere

References:

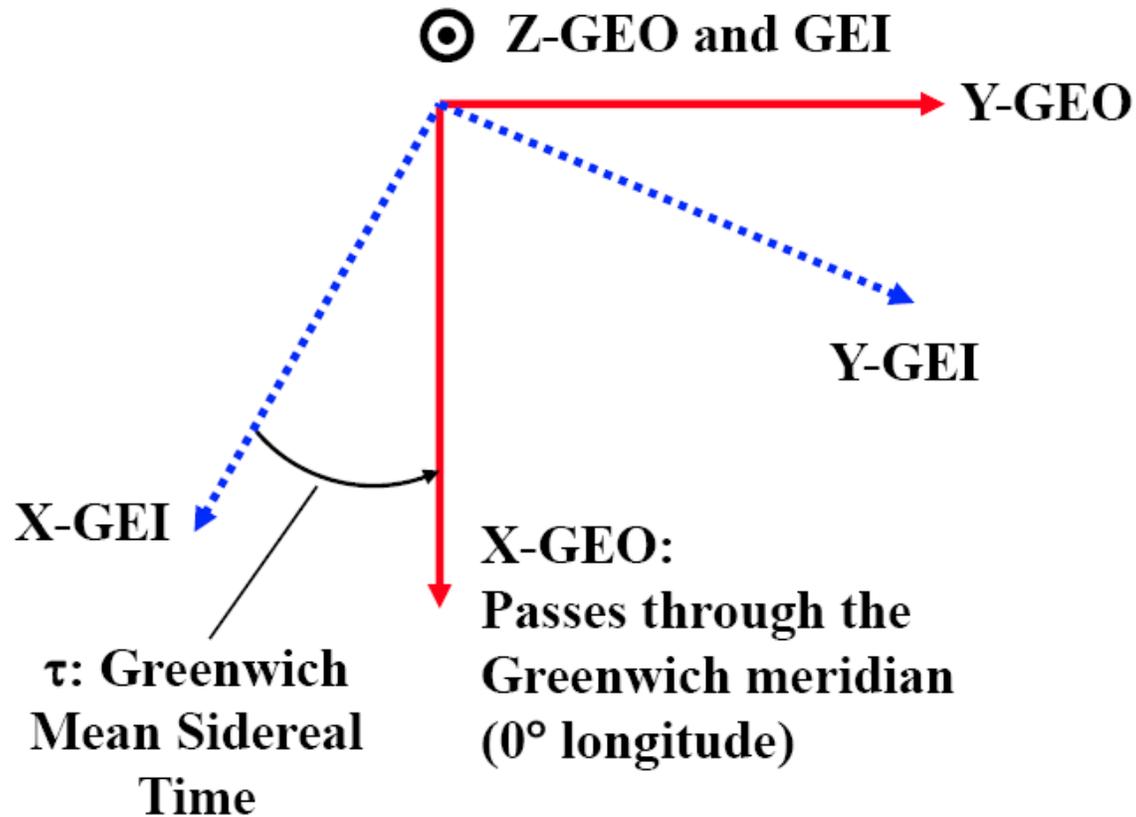
1. Introduction to Space Physics, 531-543, 1995.(edited by M. G. Kivelson and C. T. Russell)
2. <http://sscweb.gsfc.nasa.gov/>

Geocentric Equatorial Inertial (GEI) Coord.



- X: Pointing from the earth toward the first point of Aries (the position of the Sun at the vernal equinox). This direction is the intersection of the Earth's equatorial plane and the ecliptic plane.
- Z: Parallel to the rotation axis of the Earth.
- Y: Completes the right-handed orthogonal system. ($Y = Z \times X$)

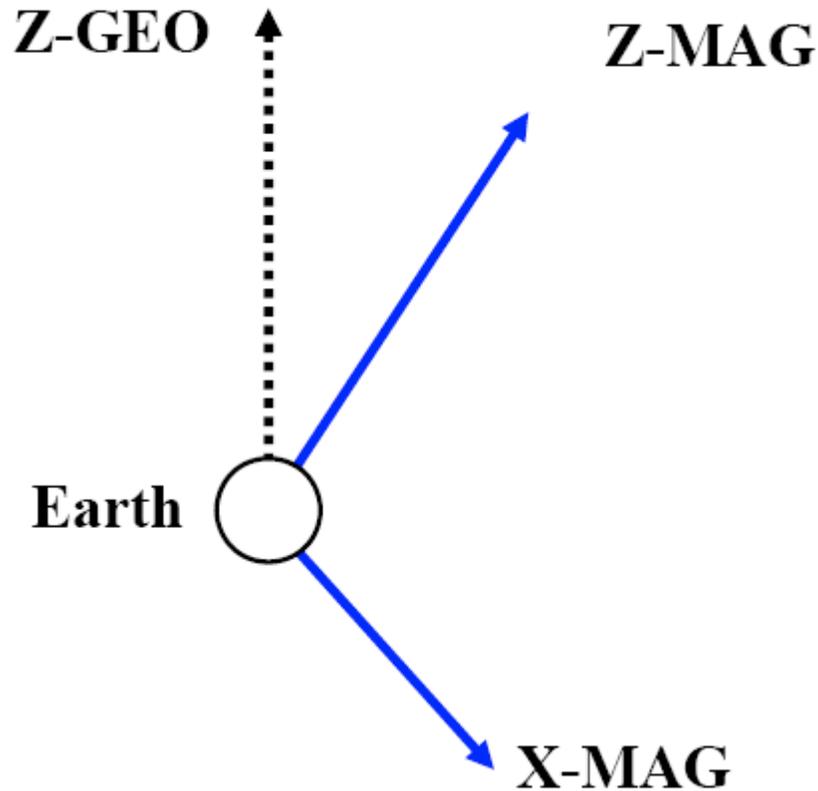
Geographic (GEO) Coord.



- X: In the Earth's equatorial plane, but fixed with the rotation of the Earth So passes through the Greenwich meridian (0° longitude).
- Z: Parallel to the rotation axis of the Earth.
- Y: Completes the right-handed orthogonal system. ($Y = Z \times X$)

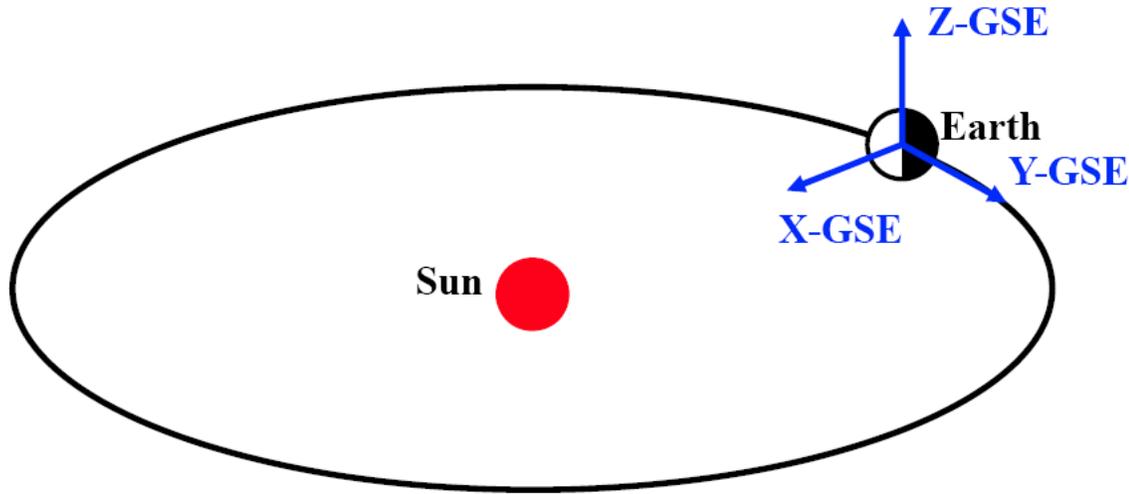
(Longitude: eastward, 0 UT = 0 LT at Greenwich meridian)

Geomagnetic (MAG) Coord.



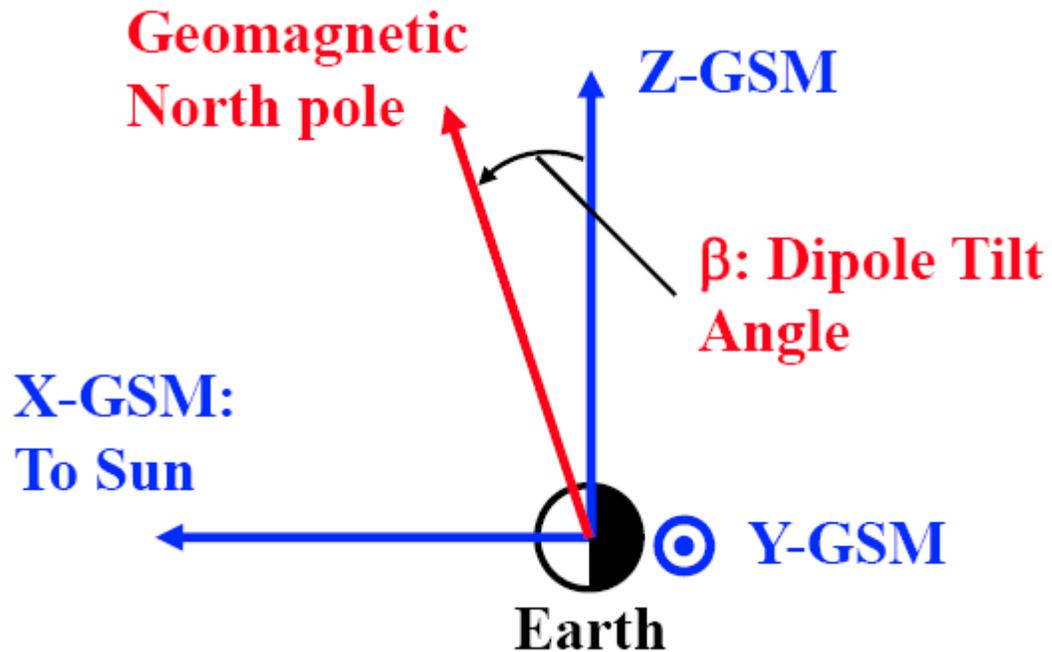
- X: Perpendicular to the Z direction.
- Z: Parallel to the geomagnetic dipole axis, positive northward.
- Y: Completes the right-handed orthogonal system. ($Y = Z \times X$)

Geocentric Solar Ecliptic (GSE) Coord.



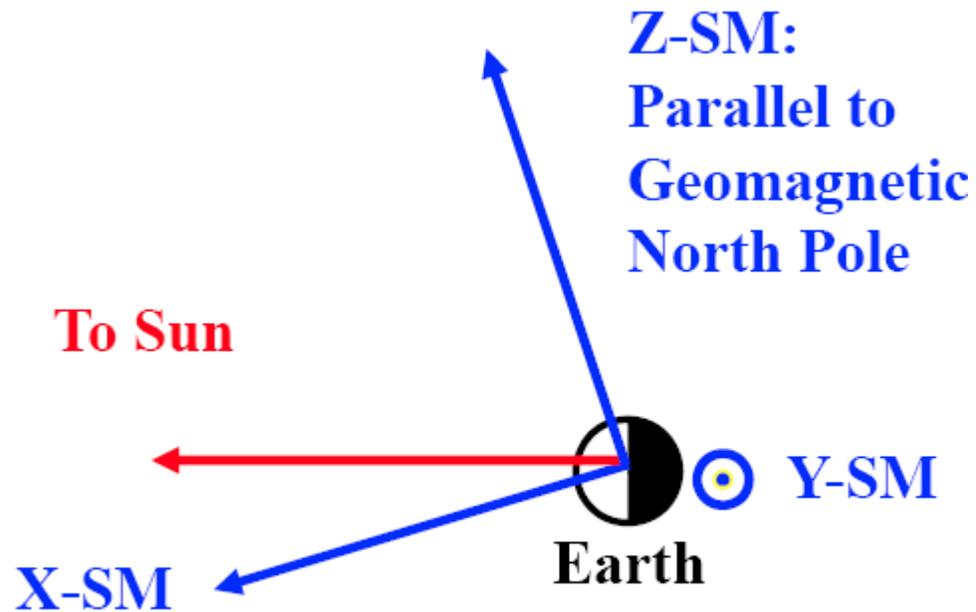
- X: Points from the center of the Earth towards the Sun.
- Z: Parallel to the ecliptic north pole.
- Y: Completes the right-handed orthogonal system. ($Y = Z \times X$)

Geocentric Solar Magnetospheric (GSM) Coord.



- X: Points from the center of the Earth towards the Sun (same as GSE).
- Y: Perpendicular to both X-axis and the Earth's dipole axis.
- Z: Completes the right-handed orthogonal system ($Y = Z \times X$).

Solar Magnetic (SM) Coord.



- Z: Points from the center of the Earth to the magnetic north pole.
- Y: Perpendicular to both Z-axis and the Sun-Earth line.
- X: Completes the right-handed orthogonal system. ($Y = Z \times X$)

2. L_{McIlwain} VS L^*

- L-shell, L-value, or McIlwain L-parameter: the set of magnetic field lines which cross the Earth's magnetic equator at a number of Earth-radii equal to the L-value.

$$L = \frac{1}{\cos^2(\lambda)}, \text{ where } \lambda: \text{ invariant latitude (= magnetic latitude)}$$

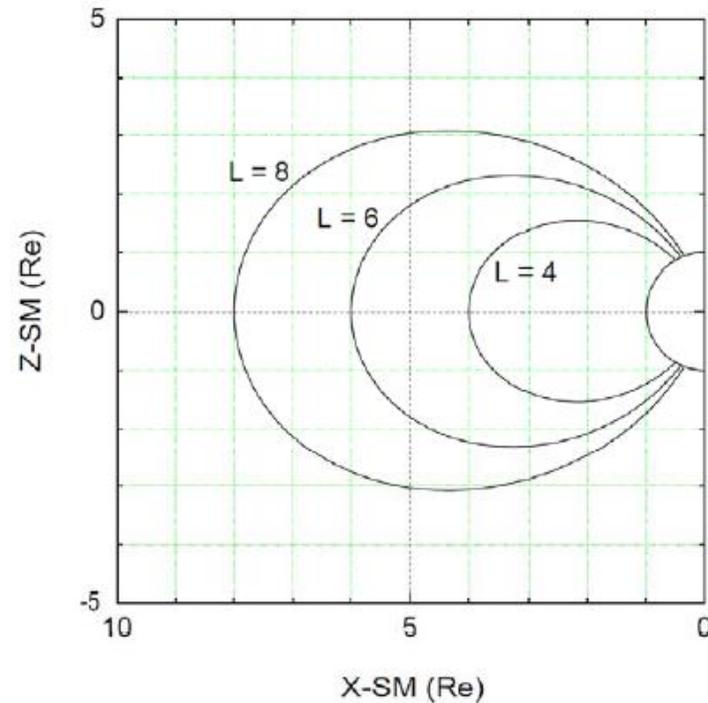
- For example, "L=4" indicates the set of the Earth's magnetic field lines which cross the Earth's magnetic equator at 4 R_e .

- L^* : the magnetic drift variant, known as the Roederer L parameter (Roederer, 1970).

$$L^* = \frac{2\pi k^0}{\Phi R_e}, \text{ where } \begin{cases} k_0: \text{ the magnetic moment of the Earth's dipole} \\ \Phi: \text{ the third adiabatic invariant in absolute value} \end{cases}$$

- In plain language, L-shell \rightarrow same field line

$L^* \rightarrow$ same drift shell



Reference:

Roederer, J. G. (1970), Dynamics of Geomagnetically Trapped Radiation, pp. 84–106, Springer, New York.